**Central System for Robotic Hand Control**

This Undergraduate student project developed a central system to control the operation of a robotic hand using various types of hands and various sensing technologies. The project simplifies the customization and configuration of smart prosthetic hands for diverse user’s needs. Provides a platform that enables the customization of smart prosthetic hands.

Presented By:

**Roei Bloch** – [roei.bloch@campus.technion.ac.il](mailto:roei.bloch@campus.technion.ac.il) , 052-3559674

**Elad Manor** – [elad.manor@campus.technion.ac.il](mailto:elad.manor@campus.technion.ac.il), 052-7480381

Ofir Tab – [ofirt@campus.technion.ac.il](mailto:ofirt@campus.technion.ac.il), 052-6336684

Supervised By:

[Tom](mailto:Tom) Sofer – [tom.sofer@technion.ac.il](mailto:tom.sofer@technion.ac.il), 054-5390355, 052-4277774

Original git link - <https://github.com/eladmanor1/Smart_Prosthesis_S24/>